

AGLP-12 Parallel Gripper

T-Slot Bearing Series, Low Profile



FEATURES AND BENEFITS

- Jaws are T-Slot bearing supported to prevent jaw breakage and offer superior load bearing performance.
- Rugged rack and pinion synchronizing.
- High gripping force to weight ratio.
- Compact design with long stroke.
- True parallel jaw motion for easy tooling.
- Units are permanently lubricated for non-lube air operation, allowing for compliance with OSHA regulations.
- Hall effect sensors are available to monitor open and closed position of the jaws.
- AGLP is fully field repairable for cost savings and minimum down time

SPECIFICATIONS

Design: Parallel, Double Acting, Synchronized Jaws

Stroke: 1.0, 1.5, 2.0 in [00.0 mm]

Gripping Force @ 80 PSI [5.5 BAR]

Closing: 80 lbs [356 N] Opening: 80 lbs [356 N]

Time:

Close: 0.25 sec [0.00 sec] Open: 0.25 sec [0.00 sec]

Pressure Range:

Low/High 10-120 PSI [.7-7 BAR]

Temperature Range:

Low/High -20°/ 180°F [-28°/ 80°C]

Side Play: ±0.000 [.00mm]

Loading Capacity:

 Max Tensile T
 Static 225 lbs 75 lbs [1001 N]
 75 lbs [334 N]

 Max Compressive C
 225 lbs 75 lbs [1001N]
 75 lbs [334 N]

Max Moment M_X 570 in/lb 190 in/lb [0.0 Nm] [0.0 Nm] Max Moment M_V 685 in/lb 228 in/lb

Max Moment M_y 685 in/lb 228 in/lb [00.0 Nm] [0.0 Nm] Max Moment M_z 570 in/lb 190 in/lb

[0.0 Nm] [0.0Nm]

Material: High Strength, Hard Coated aluminum bronze alloys, Steel

Weight: 5 lbs [2.26 KG] **Piston Diameter:** 0.000 in [00.0 mm]

January 2009 - PATENTED Made in the USA

HOW TO ORDER When ordering, please specify: Design/Model Number and Options. **TYPE** M=METRIC = IMPERIAL **SENSOR TYPE*** 1 = NPN2 = PNP**AGLP SENSOR OPTIONS SENSOR CONNECTOR STROKE OPTION** 1 = CLOSED 1 = POTTED 1000= 1.0" 2 = OPEN 2 = QUICK 1500= 1.5" 3 = BOTH2000= 2.0"

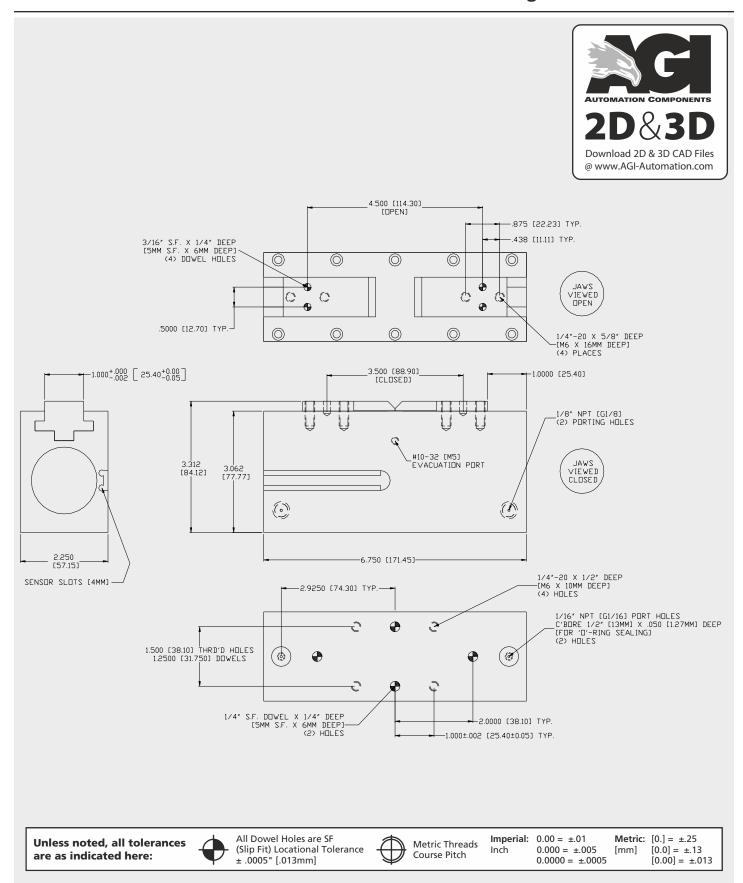
* NOTE: Hall Effect 4mm dia., 5-24 VDC, 22 mA and comes with 2 meter cable or quick disc.

Sensor Part # SHN01, SHNQ3, SHP01, SHPQ3



AGLP-12-1000 Parallel Gripper

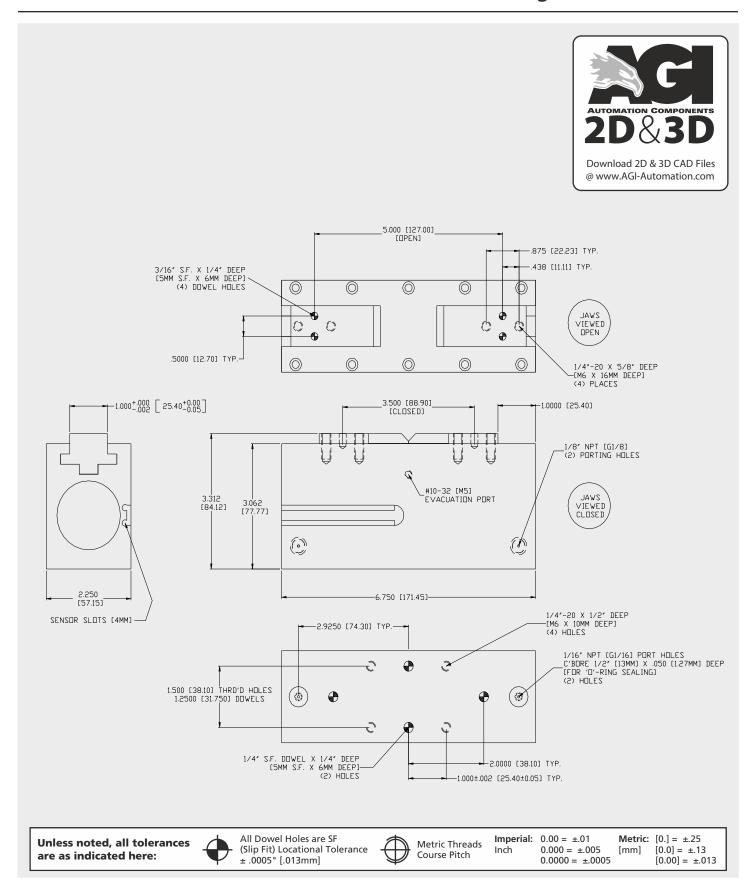
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AGLP-12-1500 Parallel Gripper

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AGLP-12-2000 Parallel Gripper

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